MECHANICAL ENGINEERING AT NATIONAL UNIVERSITY OF SINGAPORE

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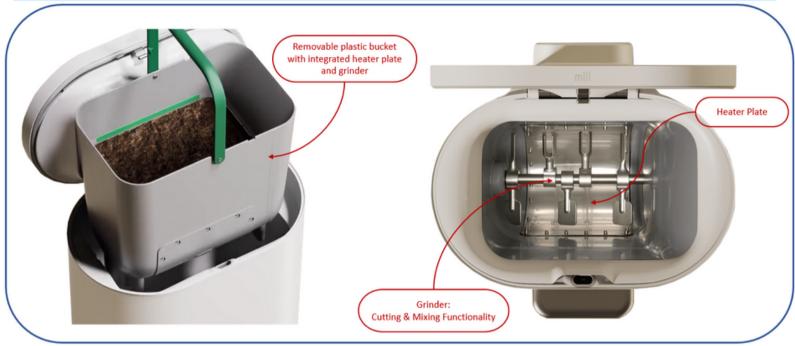
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GRINDING SYSTEM ARCHITECTURE AND DESIGN - MILL INDUSTRIES



'Designs shown here are of the first generation Mill Kitchen Bin. My work was focused on the second generation bin, which has not been released yet.

The photos here are all taken from the company website and are for illustration purposes only!

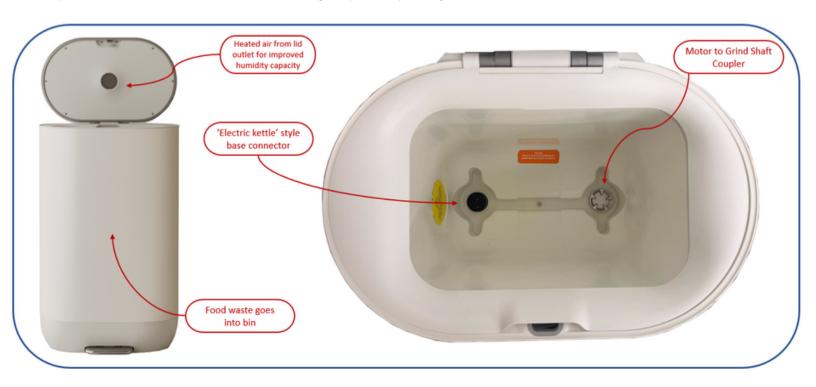
What?

- Led design and down-selection for Grinding architecture, which breaks down and dries food waste
- Validated reliability of grinding architecture through test engineering
- Designed for strong cost reduction and simplification

How?

- Collaborated with multiple teams on PD, systems architecture and test reliability from concept to production (Proto through DVT & PVT)
- Used Siemens NX for design of novel grinding shaft design and geartrain design (2 patents pending)

- Improved grinder system with effective cutting, mixing and drying
- Significant Cost reduction through DFM and part simplification
- Designs implemented into final production unit!



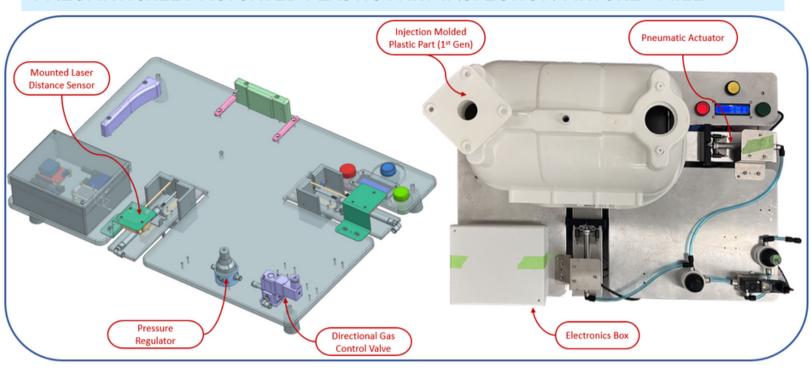
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PNEUMATICALLY-ACTUATED PLASTIC PART INSPECTION FIXTURE - MILL



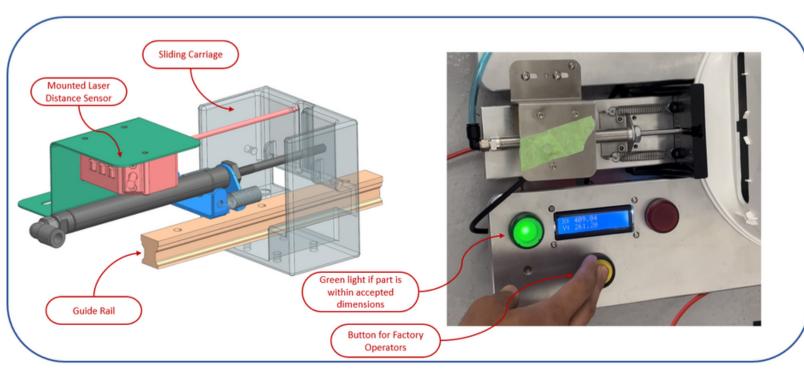
What?

- Design and fabricate the inspection fixture for injectionmolded factory parts
- Design the pneumatic actuation system through use of control valves and pressure regulators

How?

- Used Siemens NX to design all parts
- Applied DFA principles for the component location and pressure regulator mounts
- Calibration of input air pressure to minimize deflection in plastic part

- The design fulfilled its purpose well with accurate and consistent measurements, with mitigation for deviation in part placement and tolerances
- User-friendly design for factory operators
- Deployed for long term use in factory!



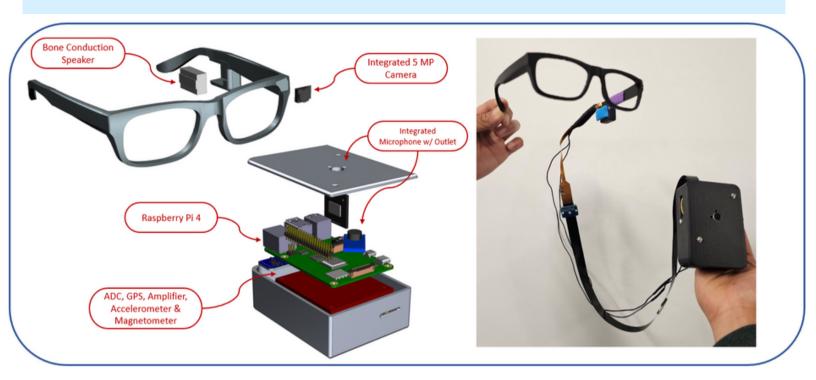
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VIDI: TRAVEL COMPANION GLASSES FOR THE VISUALLY IMPAIRED - UC BERKELEY AI HACKATHON



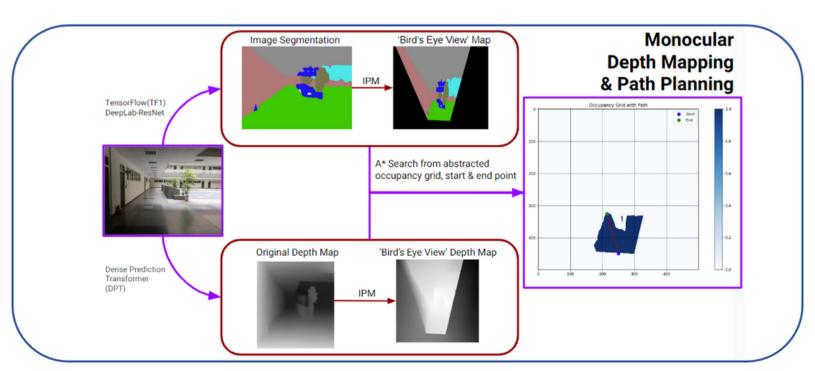
What?

- Vidi is a pair of smart glasses that utilizes the power of LLMs and sensor technologies to help guide and support the visually impaired
- It can do path planning, along with object detection & identification for the user.

How?

- Designed 3D CAD models for glasses and electronics case, with integrated sensors and connectors
- Designed customized path planning method involving monocular camera, via Inverse Projection Mapping and TF1 Image Segmentation model
- Used YoloV8 for object identification

- Successful product demo at hackathon with object detection and voice recognition!
- Comfortable, compact and user-oriented design



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RAVEN DRONE BODY PROJECT - PERFORMANCE ROTORS (PR)



What?

- Design and fabricate the housing & mounts for new electrical components for a testing drone
- Design antenna receiver mounts to minimize intrusiveness

How?

- Used SolidWorks to design my parts
- Applied **DFM principles** for the housing design
- 3D Printed all components

Results

- The design fulfilled its purpose well with a minimal part count
- Provided compact and aesthetic housing while allowing abundant airflow for fan & heatsink

NDT RAVEN DRONE BODY PROJECT - PR



What?

- Design and fabricate a compact housing for NDT components
- Ensure housing accommodates easy removal and refilling of couplant fluid bottle

How?

- Used Solidworks to design my parts
- Applied **DFM principles** for housing design
- 3D Printed all components

Results

 New design reduced manufacturing & assembly time by 45% with its minimal part count

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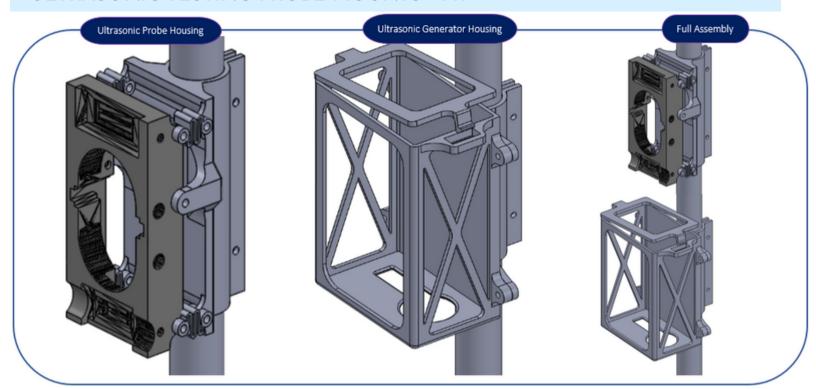
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ULTRASONIC TESTING PROBE MOUNTS - PR



What?

- Design and fabricate the housing and mounting clamps for Ultrasonic Testing (UT) equipment
- Design a compliant spring mechanism to allow for limited rotation of UT
 Probe head

How?

- Used SolidWorks to design fixture
- **Prototyping** of various spring designs to achieve target flexure
- Prototyping & extensive testing of snap fit lock and friction clamps

Results

 The UT set has been successfully deployed for On-Site NDT operations, with good reviews from the operations team



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DRONE POWDER RELEASE MECHANISM & MOUNT - PR



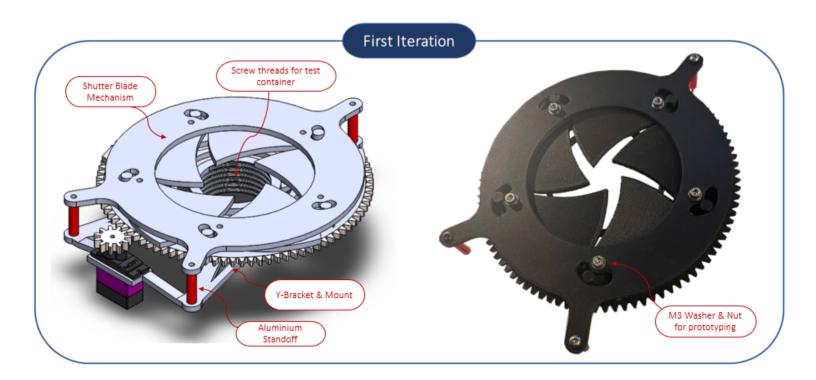
What?

- Design, Fabricate & Test a powder dispensing mechanism which mounts onto a powder payload
- Minimize number of electrical components required
- Ensure payload and dispensing mechanism can be quick-released

How?

- Produced 3D CAD models with Solidworks
- Used Solidworks Gear Toolkit to design gear system
- 3D Printed all components

- The design fulfilled its task well while minimizing weight and part count
- Design will be further iterated and presented to the private client for sale



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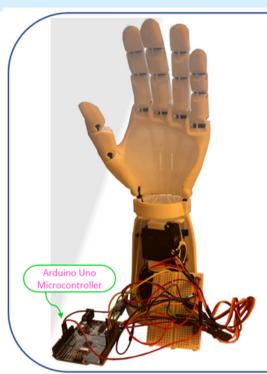
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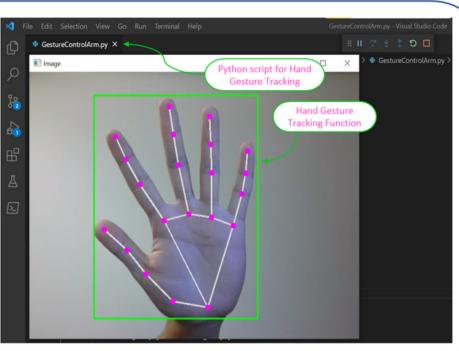
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3D-PRINTED GESTURE TRACKING ROBOT HAND





What?

- **Design, Fabricate & Assemble** a 3D-Printed Robot Hand
- Implement hand gesture tracking ability via computer vision

How?

- Improved upon open source 3D
 Robot Hand design to fix wrist joint design issues
- Used Arduino Uno for robot finger controls
- Implemented CV2 & CVZone python packages for computer vision capability

Results

 Robot Hand can track and mimic user hand gesture successfully and quickly (scale of 0.1 seconds)

Base Parts & Assembly

